

## PROBLEM SET 7 (SUPPLEMENT)

### Section 1: Lorenz Model

The Lorenz model is given by

$$\dot{X} = P(Y - X) \quad (1)$$

$$\dot{Y} = -XZ + rX - Y \quad (2)$$

$$\dot{Z} = XY - bZ \quad (3)$$

We are using `ode45` again in this problem set! This Matlab routine solves system of ODEs using the 4th order Runge-Kutta method. `lorenz.m` is provided.

Lets take a look at `lorenz.m`. The function is called `lorenz`. The next line declares that  $dy$  be a vector of length 3 and initializes to zeros. The next few lines declare the various parameters ( $P$ ,  $r$ , and  $b$ ) in the Lorenz model. Finally, the gut of the function, the specification of the 3 first order ODEs:

```
dy(1) = P*(y(2) - y(1));
dy(2) = -y(1)*y(3) + r*y(1) - y(2);
dy(3) = y(1)*y(2) - b*y(3);
```

In this problem set,  $P = 10$ ,  $b = 8/3$  and  $r$  is the primary parameter of interest to play around with. In the past, you have done this for other systems. (eg.  $\mu$  in  $x_{n+1} = 4\mu x_n(1 - x_n)$ ,  $h$  in the driven pendulum, and  $\alpha$  in the first problem of your midterm!) This diversity should give you some appreciation of the universality of these phenomena.

As given,  $r$  is set to 0.5 in `lorenz.m`. You should use an editor to change this if you want to solve the model for other values of  $r$  and REMEMBER to save your changes before running `ode45`. To start Matlab, add `matlab` and execute `matlab &`. An example run may look like

```
>> options = odeset('RelTol',1e-4,'AbsTol',[1e-6 1e-6 1e-8]);
>> tspan=0:0.01:100;
>> [t,y] = ode45('lorenz', tspan, [0.2 0.2 0.3], options);
```

The first line sets various options controlling the numerical tolerances. The second line sets the time interval and increment size. Initial conditions are:

$$X(0) = 0.2$$

$$Y(0) = 0.2$$

$$Z(0) = 0.3$$

Note that  $y$  stores all the time series for  $X, Y, Z$ , in consistent with the specification in `lorenz.m`.

```
y(:,1) is X
y(:,2) is Y
y(:,3) is Z
```

To plot various time series

```
>>plot(t,y(:,1),'-');
>>plot(t,y(:,2),'-');
>>plot(t,y(:,3),'-');
```

To plot  $XY$ ,  $XZ$ , and  $YZ$  projections as your Poincaré section

```
>>plot(y(:,1), y(:,2), '.');
>>plot(y(:,1), y(:,3), '.');
>>plot(y(:,2), y(:,3), '.');
```

To plot trajectory in 3-D.

```
>>plot3(y(:,1), y(:,2), y(:,3));
```

To see the time evolution (animation),

```
>>comet3(y(:,1), y(:,2), y(:,3));
```

To investigate exponential divergence of *small* differences in initial conditions. You should run another session of `ode45` but saving your  $XYZ$  in a different variable name than  $y$ . eg.

```
>> [t,g] = ode45('lorenz', tspan, [0.200000001 0.2 0.3], options);
```

Note the almost zero deviation from the previous run. To compute the “distance” between points in two time series

```
>> distance = sqrt((y(:,1) - g(:,1)).^2 + (y(:,2) - g(:,2)).^2 +
    (y(:,3) - g(:,3)).^2);
>>
>>
>> plot(t,log(distance));
```

An exponential divergence will correspond to a straight line with positive slope on a semilogy plot. If your plot looks irregular, you can try average over several runs of nearby ICs.

OK... hope I have given enough information on this problem set. Please let us know immediately if you experience any problems.