

# M-Structures: Programming with State and Nondeterminism

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## Lecture 12

<http://www.csg.lcs.mit.edu/6.827>

## Limitations of Functional Programming

- Forces an *obscure coding style* - threading the “state” - for some problems
- Requires too much *storage*
- Cannot express the *parallelism* in some algorithms
- Cannot express *non-deterministic algorithms*
  - histograms
  - graph traversals
- Cannot express *non-determinism inherent in*
  - access to shared resources
  - storage allocator

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## Language extensions

- I-structures: “write once” variables
  - Multiple writes cause an “inconsistency” and blowup the program. A flavor of logic variables
  - Benign side-effects but equational reasoning is weakened
- M-structures: “synchronized reads and writes”.
  - each read “empties” the variable and a write to a “full” variable causes a program blowup
  - simultaneously requires the notion of a “barrier” to control the order of evaluation of some expressions
  - equational reasoning is weakened dramatically
- Monads: a new way of manipulating programs (has become very popular in the last decade)
  - preserves equational reasoning
  - not obvious how to use it for expressing parallelism

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## I-Cell: The Simplest I-Structure

```
data ICell a = ICell {contents :: . a}
```

*Constructor*

```
ICell :: a -> ICell a
```

I-Structure field

```
ICell e           or     ICell {contents = e}
```

*or create an empty cell and fill it (a “side-effect”)*

```
ic = ICell {}
contents ic := e
```

*Selector (iFetch)*

```
contents ic      or
case ic of
    ICell x -> ... x ...
```

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## I-Cell: Dynamic Behavior

- Let allocated I-cells be represented by objects  $o_1, o_2, \dots$
- Let the states of an I-cell be represented as:

$\text{empty}(o) \mid \text{full}(o,v) \mid \text{error}(o)$

- When a cell is allocated it is assigned a new object descriptor  $o$  and is empty, i.e.,  $\text{empty}(o)$
- Reading an I-cell  
 $(x = \text{iFetch}(o) ; \text{full}(o,v)) \Rightarrow (x = v ; \text{full}(o,v))$
- Storing into an I-cell  
 $(\text{iStore}(o,v) ; \text{empty}(o)) \Rightarrow \text{full}(o,v)$   
 $(\text{iStore}(o,v) ; \text{full}(o,v')) \Rightarrow ?(\text{error}(o) ; \text{full}(o,v'))$

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## Multiple-Store Error

Multiple assignments to an I-cell cause a multiple store error

A program with exposed store error is suppose to blow up!

Program --> T

The Top represents a contradiction

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## M-Cell: The Simplest M-Structure

```

data MCell a = MCell {contents :: & a}
Constructor
MCell :: a -> MCell a
M-Structure field

MCell e           or      MCell {contents = e}

or create an empty cell and fill it

mc = MCell {}
contents mc := e          overloaded notation

Selector (mFetch)
contents & mc
pattern matching ?

```

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## M-Cell: Dynamic Behavior

- Let allocated M-cells be represented by objects  $o_1, o_2, \dots$
- Let the states of an M-cell be represented as:

$\text{empty}(o) \mid \text{full}(o, v) \mid \text{error}(o)$

- When a cell is allocated it is assigned a new object descriptor  $o$  and is empty, i.e.,  $\text{empty}(o)$
- Reading an M-cell  
 $(x = \text{mFetch}(o) ; \text{full}(o, v)) \Rightarrow (x = v ; \text{empty}(o))$
- Storing into an M-cell  
 $(\text{mStore}(o, v) ; \text{empty}(o)) \Rightarrow \text{full}(o, v)$   
 $(\text{mStore}(o, v) ; \text{full}(o, v')) \Rightarrow \text{error}(o) ; \text{full}(o, v')$

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## The Need of Barriers

Suppose we want to replace the contents of M-Cell `mc` by zero.

We need to empty it first to avoid a double store error.

First attempt:

```
let old = content & mc
    content mc := 0
in ...
```

*Correct ?*

Second attempt:

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## M-Cell: Imperative Reads and Writes

*Examine:* like a read operation

```
contents mc ≡ let v = contents & mc
                contents mc := v
            in
                v
```

*Replace:* like an update operation

```
contents & mc := e ≡
    v = e
    ( _ = v >>>
        _ = contents & mc >>>
        contents mc := v )
```

M-structures with barriers have the full expressive power of imperative languages *but the language is not sequential!*

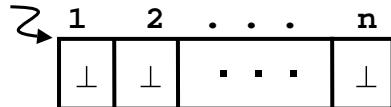
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## M-Arrays

- *Allocate*

```
x = mArray (1,n) []
```



- *Put*

```
x!2 := 5
```

A put operation on  
a full slot is an error



- *Take*

```
x!&2
```



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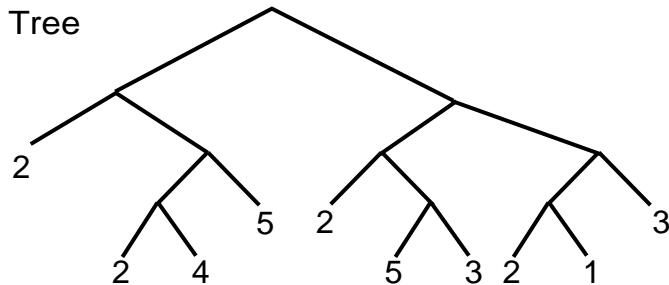
## Three Examples

- Histograms
- Inserting an element in a list
- Graph traversal

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## Histogram of Elements in a Tree



Histogram

1	2	3	4	5
1				2

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## Histogram: A Functional Solution

Thread the histogram array

```

data Tree = Leaf Int | Node Tree Tree
traverse :: Tree ->(ArrayI Int)->(ArrayI Int)
traverse (Leaf i)           hist = incr hist i
traverse (Node ltree rtree) hist =      ?
  
```

```

incr hist j =
  let inc i = if i == j then (hist!i)+1
              else hist!i
  in mkArray (bounds hist) inc
  
```

```

mkHistogram tree =
  let hist = array (1,5) [ 0 | i <- [1..5]]
  in traverse tree hist
  
```

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# *Histogram* : Using M-structures

```
mkHistogram tree =
  let hist = mArray (1,5) [ 0 | i <- [1..5]]
      ( traverse tree hist
        >>>
        hist' = hist )
  in hist'

traverse :: Tree -> (MArrayI Int) -> ()
traverse (Leaf i) hist =
  ?

traverse (Node ltree rtree) hist =
  ?
```

*No threading, No copying*  
+ Natural coding style and more parallelism

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## Mutable Lists

Any field in an algebraic type can be specified as an M-structure field by marking it with an “&”

```

data  MList t = MNil
      | MCons {hd::t, tl::&(MList t)}
      | MStruct {slot1, slot2, ...}

Allocate
x = MCons {hd = 5}                                M-structure slot

Take
tl & x

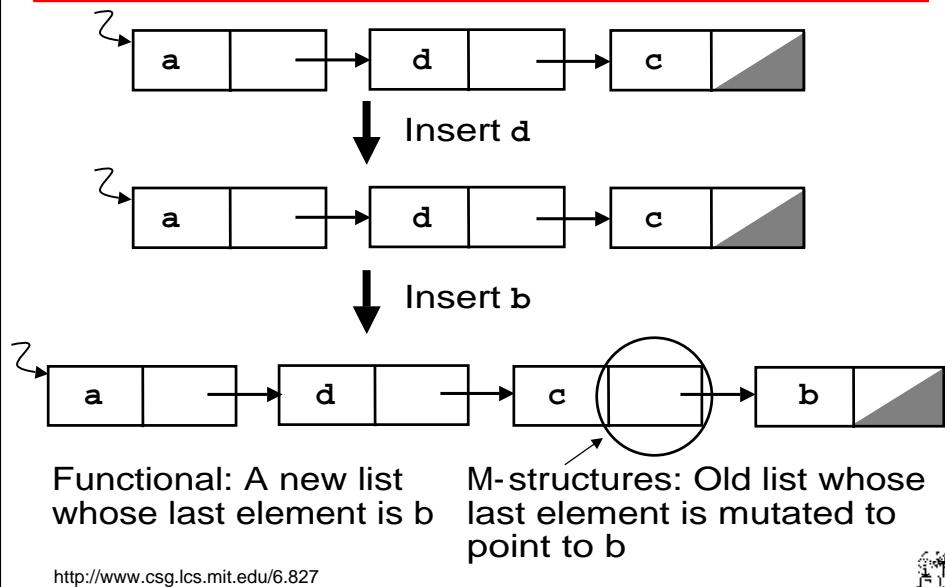
Put
tl x := v

```

*No side-effects while pattern matching*

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## Inserting an element in a list



## Insert: Functional and Non Functional

Functional solution:

```
insertf [] x = [x]
insertf (y:ys) x = if (x==y) then y:ys
                    else y:(insertf ys x)
```

M-structure solution:

```
insertm ys x =
  case ys of
    MNil      -> MCons x MNil
    MCons y ys' -> if x == y then ys
                      else ?
```



## Subtle Issues

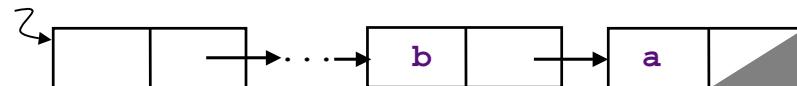
Compare

```
ys1 = insertf ys a
ys2 = insertf ys1 b
```

```
ys1 = insertm ys a
ys2 = insertm ys1 b
```

assuming **a** and **b** are not in **ys**.

**ys2** Can the following list be produced?



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## Out-of-order Insertion

```
insertm ys x =
  case ys of
    MNil          -> MCons x MNil
    MCons y ys' ->
      if x == y then ys
      else let tl ys := insertm (tl&ys) x
            in ys

  ys1 = insertm ys a
  ys2 = insertm ys1 b
```

**ys1** can be returned before the insertion of **a** is complete but **(tl&ys)** can't be read again before **(tl&ys)** is set

Can you replace **tl&ys** by **ys'**?

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## Membership and Insertion

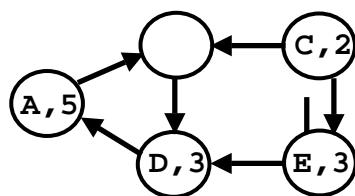
`insertm'` is the same as `insertm` except that it also returns a flag that indicates if a match was found

```
insertm' ys x =
  case ys of
    MNil      -> (False,(MCons x MNil))
    MCons y ys' ->
      if x == y then (True,ys)
      else let
        (flag,ys'') = (insertm' (tl&ys) x)
        tl ys := ys''
      in
        (flag, ys)
```

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## Graph Traversal



```
data GNode =
  GNode {id :: Nodeid,
         val :: Int,
         nbrs:: [GNode] }
a = GNode "A" 5 [b]
b = GNode "B" 7 [d]
c = GNode "C" 2 [b]
d = GNode "D" 3 [a]
e = GNode "E" 3 [c,d]
```

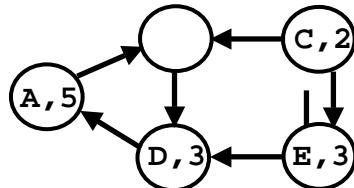
Write function `rsum` to sum the nodes reachable from a given node.

`rsuma ==> ?`

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## Graph Traversal: First Attempt



```

data GNode =
  GNode {id :: Nodeid,
         val :: Int,
         nbrs:: [GNode] }
  
```

```

rsum (GNode x i nbrs) =
  i + sum (map rsum nbrs)
  
```

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## Mutable Markings

Keep an updateable boolean flag to record if a node has been visited. Initially the flag is set to false in all nodes.

```

data GNode = GNode {id::Nodeid, val::Int,
                    nbrs::[GNode], flag::&Bool}
  
```

A procedure to return the current flag value of a node and to simultaneously set it to true

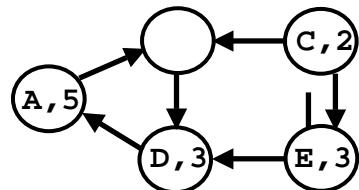
```

marked node = let m = flag & node >>
              flag node := True
            in
              m
  
```

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## Graph Traversal: Mutable Markings



```
data GNode =
  GNode {id :: Nodeid,
         val :: Int,
         nbrs::: [GNode]
         flag:::&Bool }
```

```
rsum node =
  if marked node then 0
  else
    (val node)
    + sum (map rsum (nbrs node))
```

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## Book-Keeping Information

```
data GNode = GNode {id::Nodeid, val::Int,
                    nbrs:::[GNode], flag:::&Bool}
```

*The graph should not be mutated!*

Keep the visited flags in a separate data structure -  
*a notebook* with the following functions

```
mkNotebook :: () -> Notebook
member      :: Notebook -> Nodeid -> Bool
```

Immutable (functional) notebook

```
insert :: Notebook -> Nodeid -> Notebook
```

Mutable notebook: insertion causes a side effect

```
insert :: Notebook -> Nodeid -> ()
```

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## Graph Traversal: *Immutable Notebook*

Thread the notebook and the current sum through the reachable nodes of the graph in any order

```

data GNode =
  GNode {id::Nodeid, val::Int, nbrs::[GNode]}

rsum node =
  let nb = mkNotebook ()          -- a new notebook
    (s,_) = thread (0, nb) node
    thread (s,nb) (GNode x i nbs) =
      if member nb x then (s,nb)
      else let nb' = insert nb x
            s' = s + i
            in s
  in s

```

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## Graph Traversal: *Mutable Notebook*

```

rsum node =
  let nb = mkNotebook ()          -- a new notebook

  rsum' (GNode x i nbs) =
    if (member nb x) then 0
    else let
      insert nb x >>>
      s = i + sum (map rsum' nbs)
      in s
  in rsum' node

```

- *No threading*
- *No copying*

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