R13

Code No: 117EA	KIS
JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY B. Tech IV Year I Semester Examinations, November/Dece INSTRUMENTATION AND CONTROL SYSTEM	mber - 2016.:
(Common to ME, AME)	34 34 39 77
Time: 3 Hours	Max. Marks: 75
Note: This question paper contains two parts A and B. Part A is compulsory which carries 25 marks. Answer all question are a sub-question carries 10 marks and may have a, b, c as sub questions.	nestions in Part A.
PART- A	
	(25 Marks)
1.a) Distinguish between Accuracy and Precision: b) State and explain briefly desirable and undesirable dynamic characteristics of manometer fluid. c) List out active transducers. d) State the characteristics of manometer fluid. e) List out contactless electrical tachometers.	[2] [3] [2] [3] [2]
f). What is the relationship between the rotational speed and the flash directed onto a single radial mark on the rotating wheel? g) State the factors to be considered for the selection of material used	aing rate of stroboscope
h) Draw the neat diagram of Sling psychrometer and mention composition in State any two merits of closed loop control systems. Distinguish between servomechanism and process control.	
PART-B	
PARI-B	(50 Marks)
2.a): Draw the generalized scheme of a typical measurement system and components of it.	d explain atious various
b) State and explain various types of errors in measurements. OR	[5+5]
3.a) Draw the block diagram of first order system. Derive the equation the first order system.	1
b) Derive the steady-state responses of first order system with respection i) Step input and ii) Ramp input.	to:
4. Explain the construction and principle of LVDT with a neat diagracapacity pickup transducer.	am and compare it with [10]
 5.a) Explain the working principle of Bimetallic thermometer with a respectively. If its resistance becomes 305.3 Ω when it is in a determine the temperature of the gas. Take the temperature coe 0.0039⁰C⁻¹. 	$100.0 \ \Omega$ at $100 \ \text{and} \ 0^{0} \text{C}$ contact with a hot gas,